

Connected Vehicles: How Wireless Technology can Transform Transportation Safety

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The Problem

Safety

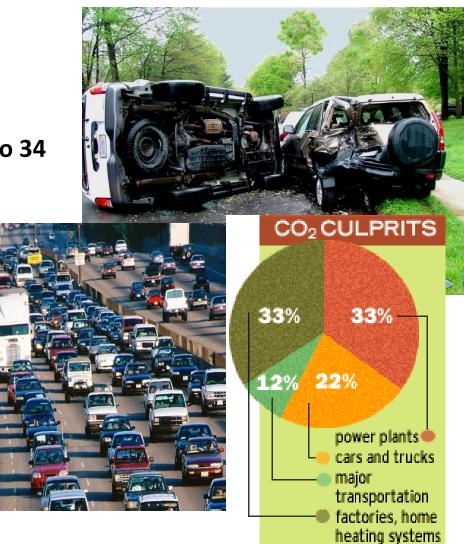
- 32,788 highway deaths in 2010
- 6,000,000 crashes/year
- Leading cause of death for ages 4 to 34

Mobility

- 4,200,000,000 hours of travel delay
- \$80,000,000,000 cost of urban congestion

Environment

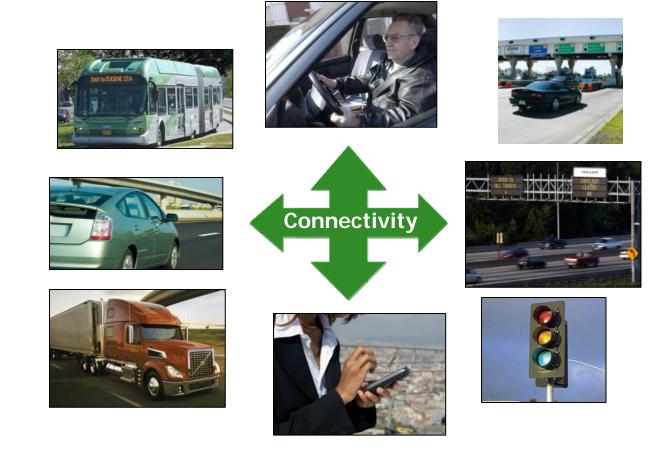
 2,900,000,000 gallons of wasted fuel





ITS Research = Multimodal and Connected

Drivers/Operators



Wireless Devices



nfrastructure

What is the Connected Vehicle Program

- Vehicle-to-vehicle and vehicle-to-infrastructure wireless communications for:
 - Crash prevention
 - Improved mobility
 - Environmental sustainability
- Over 80% of unimpaired crash scenarios addressed by connected vehicle capability



- Encompasses autos, buses, and trucks
- Uses wireless communications
 - Dedicated Short-Range Communications (DSRC) technology using FCCdedicated spectrum that is essential for safety applications
 - Other communications types for non-safety applications
- Research is maturing such that NHTSA has committed to an agency decision regarding whether the safety technology is sufficiently developed to support rulemaking



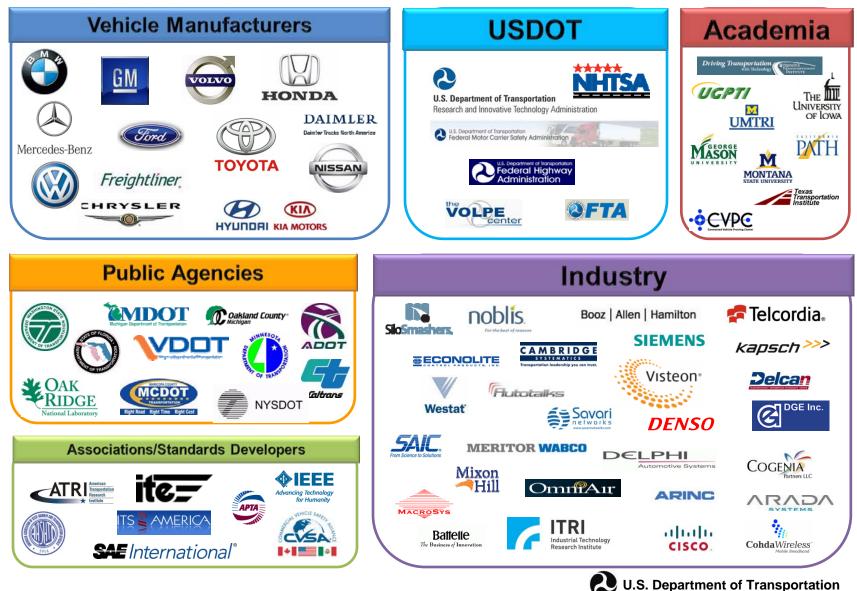
The Connected Vehicle Environment



- Uses wireless communications
 - Dedicated Short-Range Communications (DSRC) technology using FCC-dedicated spectrum that is essential for safety applications
 - Other communications types for non-safety applications



Connected Vehicle Safety Program Partners and Contractors



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ITS Research Program Components



Harmonization of International Standards & Architecture

Human Factors

Systems Engineering

Certification

Test Environments

Policy

Technology

Deployment Scenarios

Financing & Investment Models

Operations & Governance

Institutional Issues



Key Program Objectives

- 2013 Decision on Vehicle Communications for Safety (light vehicles)
- 2014 Decision on Vehicle Communications for Safety (heavy vehicles)
- 2015 Infrastructure Implementation Guidance





NHTSA Agency Decision

- Possible decision options include:
 - Rulemaking on minimum performance requirements for vehicle communications for safety on new vehicles
 - Inclusion in NHTSA's New Car Assessment Program to give car makers credit for voluntary inclusion of safety capability in new vehicles
 - More research required
- Data will determine NHTSA's action for the 2013 decision point:
 - Simulation and modeling efforts based upon previous field operational tests
 - Data collection from vehicle-to-vehicle test track testing
 - Empirical data obtained from Safety Pilot
 - Driver clinics (user acceptance)
 - Model deployment activities (safety effectiveness)
- A key factor for the NHTSA decision will be the need for, and timing of, necessary infrastructure for communication security (still undefined)



Safety Pilot Objectives

- Generate empirical data for supporting 2013 & 2014 decisions
- Show capability of V2V and V2I applications in a real world operating environment using multiple vehicle types
- Determine driver acceptance of vehicle-based safety warning systems
- Assess options for accelerating the safety benefits through aftermarket and retrofit safety devices
- Extend the performance testing of the DSRC technology
- Collect lots of data and make it available for industry wide use
- Let others leverage the live operating environment





Safety Pilot Sites

Driver clinics

□ Assess user acceptance



 Obtain empirical safety data for estimating safety benefits



Six Driver Clinic Sites





User Acceptance - Driver Clinics

- 6 locations across the US beginning in August 2011
- 100 drivers per locations
- Experience Crash
 Warnings
 - □ Forward Crash Warning
 - Emergency Brake Light
 - Blind Spot Warning
 - Lane Change Warning
 - Intersection Assist
 - Do Not Pass Warning





Progress - Step Two - Demonstrate Safety

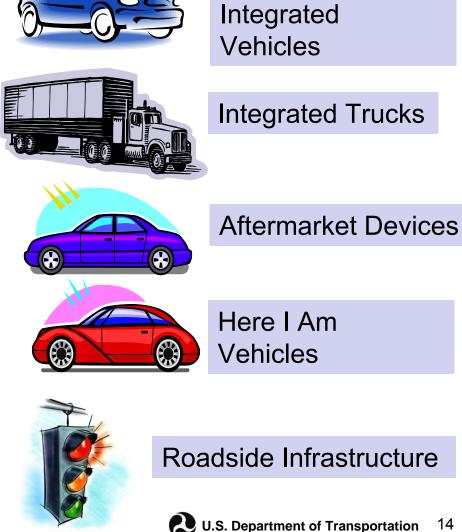
Six Scheduled Driver Clinics

 Aug'11 - Brooklyn, MI
 Sep'11 - Minneapolis, MN
 Oct'11 - Orlando FL
 Nov' 11 - Blacksburg, VA for DAC and Washington DC for the demo
 Dec'11 - Dallas, TX
 Jan'11 - San Francisco, CA



Model Deployment: Ann Arbor, MI

- Major road test and real world implementation taking place 2011 thru 2013, involving:
 - Approximately 3000 vehicles
 - Multiple vehicle types
 - Fully integrated systems and aftermarket devices
 - Roadside infrastructure
 - System wide interoperability testing
- Also to test
 - Prototype security mechanisms
 - Device certification processes



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Aftermarket Safety Devices

- Devices that transmit and receive Basic Safety Message
 - Driver interface for safety warnings
 - No integration with vehicle
- 4 vendors currently underway
- Applications include:
 - CICAS-V (red light warning) (V2I)
 - Curve overspeed warning (V2I)
 - Emergency electronic brake light (V2V)
 - Forward collision warning (V2V)
- QPL projected for March 2012
- <u>Safety devices must comply with NHTSA driver interface</u> <u>criteria before being released to drivers for model deployment</u>





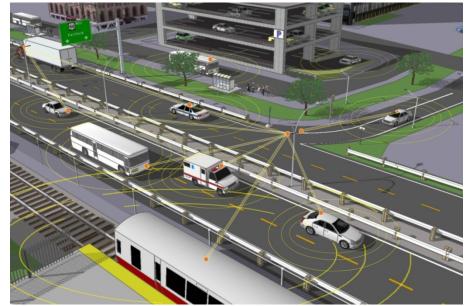
Basic Communication Devices

- Devices that only transmit Basic Safety Message
 - No driver interface
- Initial procurement resulted in 8 awards
 - o 6 vendors made it to acceptance testing
 - $\hfill\square$ No vendors fully complied with the tests
 - Specification was considered by DOT as still weak
 - Updated specification and issued 2nd procurement
- 2nd procurement resulted in 4 awards
- Qualified Products List (QPL) estimated to be established later this year



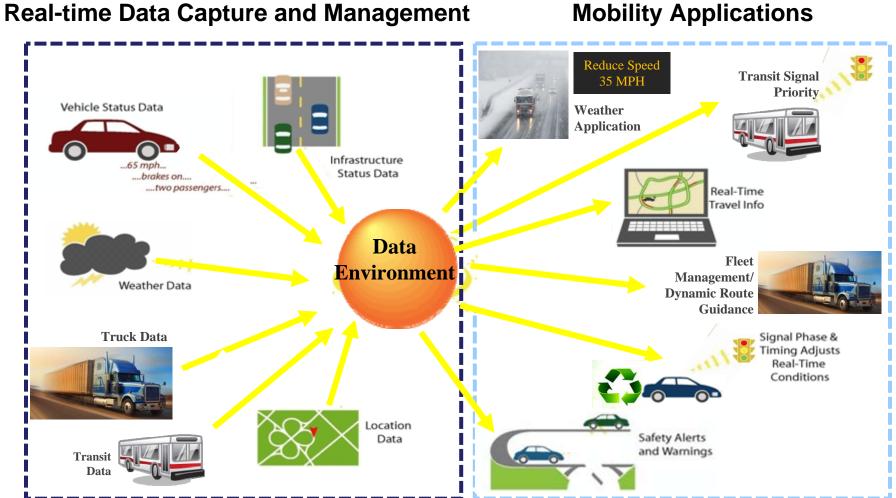
Roadside Equipment for Safety

- Transmission and receipt of V2I messages
 - Interfaces with signal controller (at intersections)
 - Supports other dangerous road segment applications
- Applications supported
 - CICAS-V (red light warning)
 - Curve overspeed warning
 - Collection of probe data transmissions
 - \Box Other (tbd)
- 4 vendors currently underway
- QPL projected for January 2012





Mobility Program



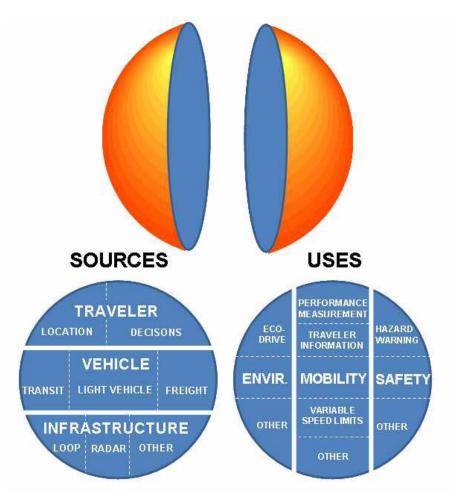
Mobility Applications

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Data Capture and Management

 ITS JPO is developing and collecting well-documented, quality data sets available from recent or ongoing operations, field tests, or simulations of emerging technologies supporting mobility, environment, transit, freight, weather, and other surface transportation research, that can be made broadly available to support dynamic mobility applications development by researchers



Environmental Program

Applications for the Environment: Real-Time Information Synthesis (AERIS)

- Recently made 7 awards to further innovative applications and concepts building on existing outside research
- Initial research results available this fall
- 2011 Plans to complete State of the Practice Scans:
 - Research of ITS and the Environment
 - Evaluation Techniques for ITS and the Environment
 - Activity-Based Travel Models
 - Environmental Models
 - Data Acquisition Technologies
- Develop Research and Analysis Framework
- Start analytics and modeling research





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Dedicated Short Range Communications

- Replaces Expensive Onboard Sensors
- Dedicated Short Range Communications (DSRC)
 - 5.9 GHz
 - Low Latency
 - ~300m Range
- Positioning
 - GPS
 - Relative Positioning (V2V)
 - Absolute Positioning (V2I)
 - High Accuracy DGPS not required
- No Digital Map Required



- Cost
- Effectiveness
- Interoperability
- Security
- Privacy

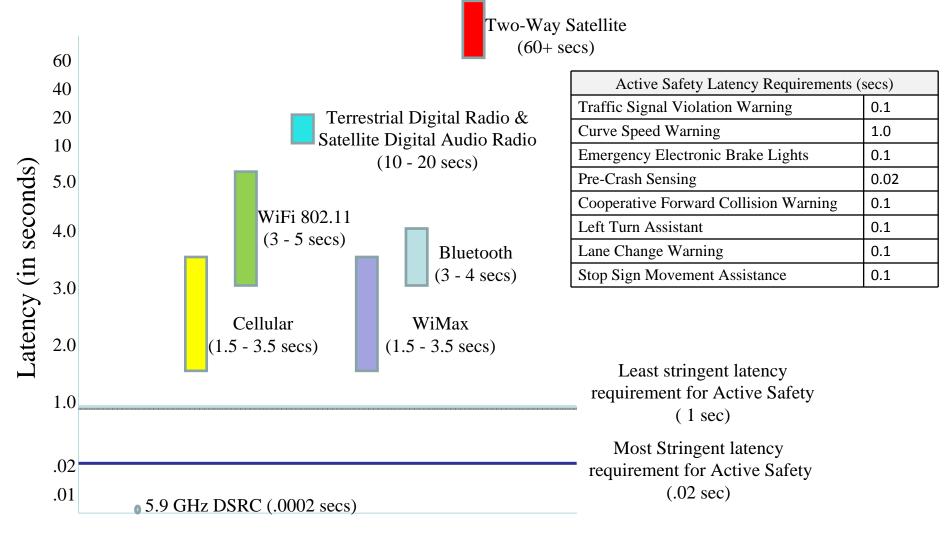


Communications Requirements

Communications Requirements	Safety (V2V and intersection crash avoidance)	Mobility and Environment	
Range	 Short range is a requirement Very high update rate (e.g., 10x per second) 	 Short range for intersection messages and toll tags, otherwise no requirement 	
Latency	 Very low latency (≤0.1 seconds) for V2V crash warning 	 Low (tolling) to high (traveler information) 	
Message Size	 Small (100-few thousand bytes) 	 Small (tolling, probe) to large (navigation updates) 	
Update Rate	 High (10x per second or higher) 	• Low	
Reliability	Very high (safety of life)	 High for tolling (accurate billing), moderate otherwise 	



Communications Technologies



Note: Y-axis not to scale for illustration purposes

Data source: Vehicle Safety Communications Project - Final Report

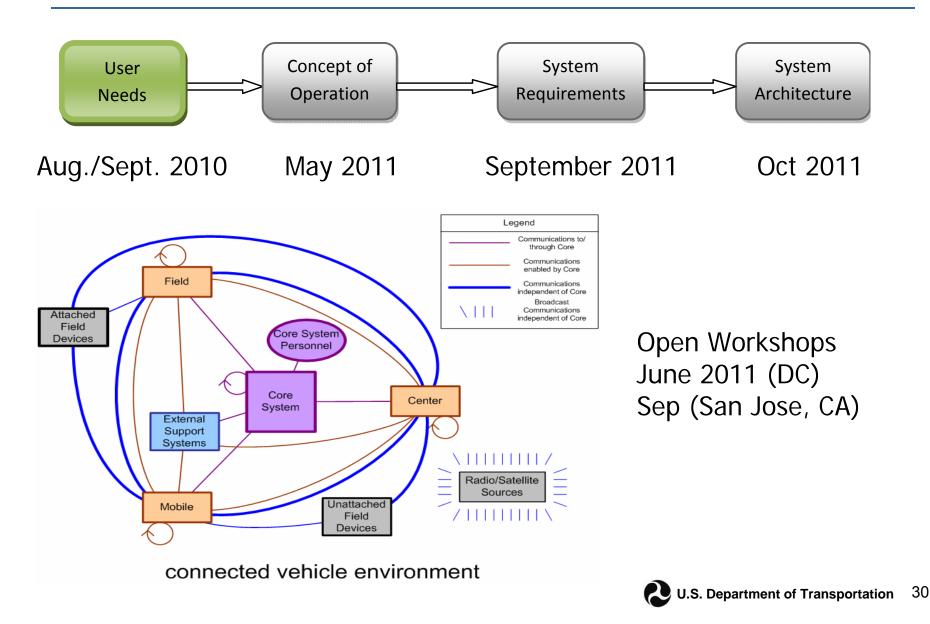
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Allocation and Band Plan

- DSRC allocation is 75 MHz in the 5.9 GHz band
- Band is for low power, short-range vehicle to vehicle and vehicle to roadside applications; shared by the public and private sector
- Six Service Channels and one control channel
- One service channel reserved for safety of life and public safety use
 - Not restricted to vehicle-to-vehicle or low latency applications
- One service channel reserved for high power (2x low power) public safety, safety of life and property applications
 - Not restricted to long range applications



Define the System and Establish a Testing Environment



Build a Reference Implementation

2011

 Test bed is Up and Running. Interoperable equipment in California, Florida, New York, Michigan, Virginia, and Network Operations in Tennessee

2012 to 2013

- Reflect the System Architecture
- Utilize Harmonized International Standards
- Implement a Certification Process
- Implement a Governance Process
- Implement a Security Process





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Deployment Scenarios

V2V Security Network

- <u>DSRC for security</u>: Estimated at 40,000 RSEs; not necessarily owned/operated by Federal/State/local governments
- Cellular or WiFi: Infrastructure exists; must address privacy
- <u>No infrastructure</u>: Unlikely to meet our needs but worthy of consideration

No easy option

All require a sustainable funding stream & governance structure All under study

V2I Infrastructure could be implemented for spot locations

- Intersections
- Curves



Privacy

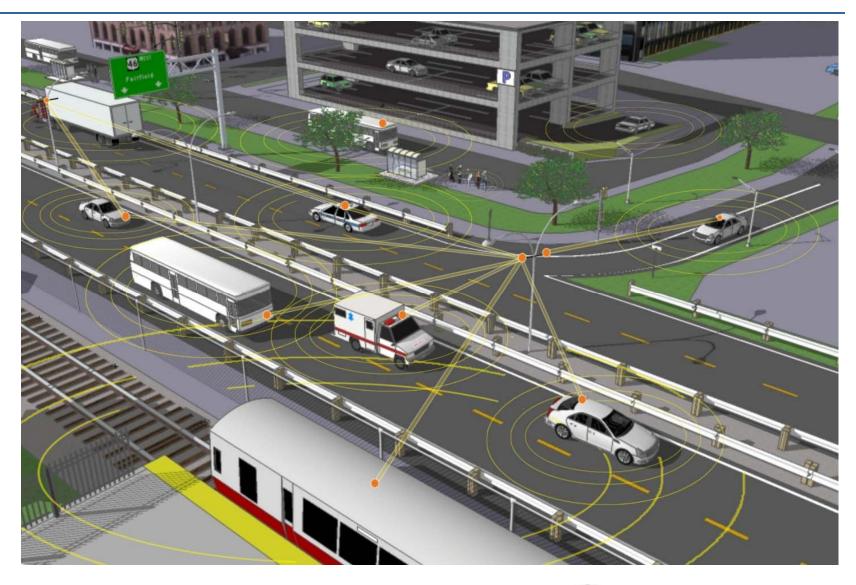
A key concern from program beginning!

- Privacy principles and policy framework developed with privacy experts, interest groups and primary program stakeholders early in program
- Addresses collection, storage and use of personal information
- Consistent with Fair Information Practices Principles used in federal government
- Basis for program decision-making and architecture development
- Continuing to engage privacy experts and interest groups in review of program architecture and plans throughout



Vehicle to Vehicle Safety Application Research Plan								
CY 2009	CY 2010	CY 2011	CY 2012	CY 2013				
Complete CAMP-V SC	-A				TRACK 0 Current Activities			
Update Crash Scenarios	Define Initial Performance Requirements				TRACK 1 Crash Scenario Frame Work			
Vehicle Communications System Engineering	Complete Message Communication Standards Security & Privacy (Certif		ntication Development Tests	Final Standards & Protocols	TRACK 2 Interoperability			
	P M D T A	efine erformance leasures evelop Objective ests dapt ACAT lethodology	Safety Pilot Performance Requirements Conduct Objective Tests	Safety Benefits Estimate	TRACK 3 Benefits Assessment			
		Develop & Build Application Vehic	Prototype Safety cles		TRACK 4 Application Development			
	DVI Effectiveness – Multiple Warnings	Driver Workload Issues	Driver Acceptance		TRACK 5 Driver Issues			
Vehicle Communications Privacy Principles	Security & Privacy Policy		Business Models	Governance (V2V)	Track 6 Policy Issues			
Update Crash Scenarios	(V2V) Define Initial Performance Reqs and Measures	Develop and Conduct Objective Tosts	Driver Workload Issues and Field Tests	CV Agency Decision	Track 7 Commercial Vehicle			
Update Crash Scenarios	Define Initial Performance Reqs and Measures	Develop and Conduct Objective Tests	Driver Workload Issues and Acceptance Field Tests	FTA Implementation Decision (TBD)	Track 8 Transit Vehicle			

Connected Transportation





For More Information



